

EE 713 Problem Set #1 Solutions - Spring 04

Problem 1

- (a) Direct transmission. GPS is actually slightly affected by the ionosphere, only important because it is a very high precision system - Atmospheric absorption usually negligible.
- (b) Direct + Earth reflections since a car must be near the ground - Other mechanisms unlikely to have much effect, mainly multipath off of surrounding objects.
- (c) AM daytime \rightarrow groundwave. Most everything else is negligible.
- (d) FM out of line of sight \rightarrow terrain diffraction. Maybe ducting in some cases.
- (e) HF \rightarrow ionospheric reflection.

Problem 2

(a) From notes, $\underline{X}(\omega) = \int_0^{\infty} du e^{-j\omega u} f(u) = A \int_0^{\infty} du e^{-j\omega u} e^{-u/\tau_1}$ ← note error in eq (2.33) p39 in notes

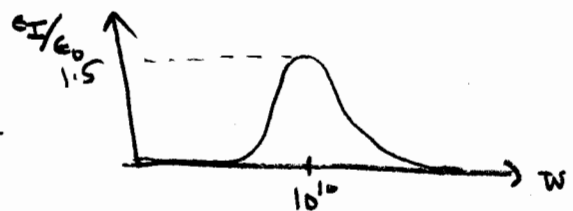
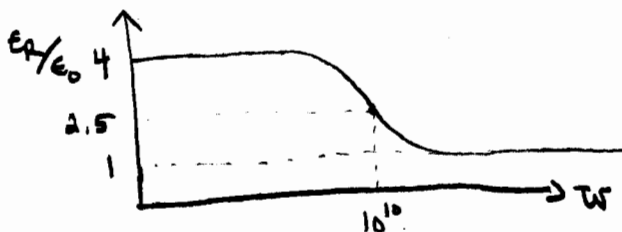
$$= A \int_0^{\infty} du e^{u(-j\omega - 1/\tau_1)} = \frac{A}{-j\omega - 1/\tau_1} e^{u(-j\omega - 1/\tau_1)} \Big|_{u=0}^{u=\infty}$$

$$= \frac{A}{1/\tau_1 + j\omega} = \frac{A\tau_1}{1 + j\omega\tau_1} = \frac{3}{1 + j(\omega \times 10^{-10})}$$

(b) If $\omega \ll 10^{10}$, the $\omega \times 10^{-10}$ term is negligible compared to 1 and we get $\underline{X}(\omega) = 3 = A\tau_1$

(c) $\underline{\epsilon} = \epsilon_0 (1 + \underline{X}(\omega)) = \epsilon_0 \left(1 + \frac{3}{1 + j\omega\tau_1/10^{10}} \right) = \epsilon_0 \left(\frac{4 + j\omega\tau_1/10^{10}}{1 + j\omega\tau_1/10^{10}} \right)$

$$= \epsilon_0 \left(\frac{4 + j\omega\tau_1/10^{10}}{1 + j\omega\tau_1/10^{10}} \right) \left(\frac{1 + j\omega\tau_1/10^{10}}{1 + j\omega\tau_1/10^{10}} \right) = \epsilon_0 \left(\frac{4 + \omega^2\tau_1^2/10^{20} + j3\omega\tau_1/10^{10}}{1 + \omega^2\tau_1^2/10^{20}} \right) = \epsilon_R - j\epsilon_I$$



Problem 2 cont'd

(d) $f = 1 \text{ GHz} \rightarrow \omega = 2\pi \times 10^9 \text{ rad/s}$

$$\underline{E} = \epsilon_0 \left(\frac{4 + \frac{\omega^2}{10^{20}} - j3\frac{\omega}{10^{10}}}{1 + \frac{\omega^2}{10^{20}}} \right) = \epsilon_0 (3.15 - j1.35)$$

$$\underline{k} = \omega \sqrt{\mu \epsilon} = \frac{\omega}{c} \sqrt{3.15 - j1.35} = 37.98 - j7.796$$

Field goes as $e^{-j\underline{k} \cdot \underline{x}} = e^{-j(37.98 - j7.796)x}$

In one meter this is $e^{-j37.98} e^{-7.796} = \boxed{2176^\circ \text{ phase shift, } 4.11 \times 10^{-6} \text{ amplitude}}$

or $20 \times \log_{10}(\text{Amplitude}) \leftarrow \text{this is a field!} \rightarrow -67 \text{ dB}$.

Problem 3

(a) 900 MHz in free space: $k = \frac{\omega}{c} = \frac{2\pi \times 9 \times 10^8}{3 \times 10^8} = 6\pi \quad \lambda = \frac{2\pi}{k} = \frac{1}{3} \text{ m}$

(b) From exponent, $\hat{k} = (\hat{y} + \hat{z})/\sqrt{2}$

(c) $\underline{H} = \frac{\hat{k} \times \underline{E}}{\eta_0}$ for a propagating wave in free space,

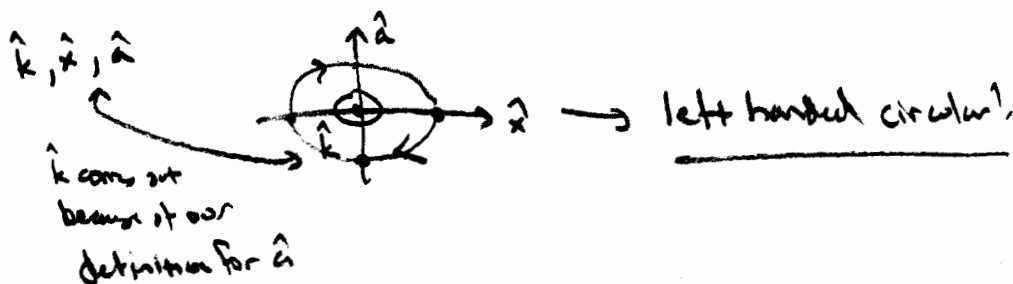
$$= \frac{1}{\eta_0} (\hat{x} + j\hat{y}) \times (\hat{y} - \hat{z}) e^{-j k(y+z)/\sqrt{2}}, \quad \eta_0 = 120\pi$$

(d) Find unit vectors \perp to \hat{k} : one is \hat{x} , other is $\hat{z} \times \hat{x} = (\hat{y} - \hat{z})/\sqrt{2} \equiv \hat{a}$

Our electric field is then $\underline{E} = (\sqrt{2}\hat{x} + j\sqrt{2}\hat{a})$ so it is circular.

To decide handedness, convert to time domain at $y+z=0$

$$\underline{E}(t) = \sqrt{2}\hat{x} \cos(\omega t) - \sqrt{2}\hat{a} \sin(\omega t)$$



Problem 4

$$\begin{aligned}
 (a) \langle \bar{S}(t) \rangle &= \frac{1}{2} \text{Re} \{ \underline{E} \times \underline{H}^* \} = \frac{1}{2} \text{Re} \left\{ \hat{\theta} \frac{j \eta_0 k \underline{I} d}{4\pi r} e^{-jkr} \sin \theta \times \hat{\phi} \frac{j k \underline{I} d}{4\pi r} e^{jkr} \sin \theta \right\} \\
 &= \frac{1}{2} \text{Re} \left\{ \frac{k^2 \eta_0 |\underline{I}|^2 d^2}{(4\pi)^2 r^2} \sin^2 \theta \right\} = \frac{k^2 \eta_0 |\underline{I}|^2 d^2}{32\pi^2 r^2} \hat{r} (\sin^2 \theta)
 \end{aligned}$$

(b) Integrate over a sphere radius R

$$\begin{aligned}
 P_r &= \int_0^\pi d\theta \int_0^{2\pi} d\phi \sin \theta (R^2) \langle \bar{S}(t) \rangle \cdot \hat{r} \\
 &= \int_0^\pi d\theta \int_0^{2\pi} d\phi \sin \theta (R^2) \frac{k^2 \eta_0 |\underline{I}|^2 d^2}{32\pi^2 R^2} \sin^2 \theta
 \end{aligned}$$

$$= \int_0^\pi d\theta \int_0^{2\pi} d\phi \frac{k^2 \eta_0 |\underline{I}|^2 d^2}{32\pi^2} \sin^3 \theta$$

$$= \frac{k^2 \eta_0 |\underline{I}|^2 d^2}{16\pi} \underbrace{\int_0^\pi d\theta \sin^3 \theta}$$

$$\int_0^\pi d\theta \sin \theta (1 - \cos^2 \theta) = \int_0^\pi d\theta \sin \theta - \int_0^\pi d\theta \sin \theta \cos^2 \theta$$

$$P_r = \frac{k^2 \eta_0 |\underline{I}|^2 d^2}{16\pi} \left(\frac{4}{3} \right)$$

$$\int_{-1}^1 du u^2 = \frac{4}{3}$$

for $u = \cos \theta$

$$(c) R_{rad} = \frac{2P_r}{|\underline{I}|^2} = \frac{k^2 \eta_0}{8\pi} d^2 \left(\frac{4}{3} \right) = \frac{k^2 \eta_0}{6\pi} d^2 \approx 20 k^2 d^2$$

$$\begin{aligned}
 (d) D(\theta, \phi) &= \frac{\bar{P}_\theta}{\eta_0 \sin^2 \theta / 4\pi r^2} = \frac{P_\theta}{P_r / 4\pi r^2} = \frac{k^2 \eta_0 |\underline{I}|^2 d^2 / 32\pi^2 r^2 \sin^2 \theta}{k^2 \eta_0 |\underline{I}|^2 d^2 / 64\pi^2 r^2} \left(\frac{3}{4} \right) \\
 &= \frac{3}{2} \sin^2 \theta, \text{ directivity} = 1.5
 \end{aligned}$$

$$(e) A_e = \frac{D \lambda^2}{4\pi} \text{ if lossless} = \left(\frac{3}{2} \sin^2 \theta \right) \frac{\lambda^2}{4\pi} = \frac{3 \lambda^2 \sin^2 \theta}{8\pi}$$